

# Wavelet Basics

(A Beginner's Introduction)

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Some references:

Marron, J. S. (1999) "Spectral view of wavelets and nonlinear regression", *Bayesian Inference in Wavelet-Based Models*, Müller, P. and Vidakovic, B. Eds., Lecture Notes in Statistics No. 141, Springer, New York, 19-32.

Strang, G. (1989) Wavelets and dilation equations: a brief introduction, *SIAM Review*, 31, 614-627.

For deeper mathematics, but concisely presented: Chps. 1 and 2 of:

Benedetto, J. J. and Frazier, M. W. (1994) *Wavelets: Mathematics and Applications*, CRC Press, Boca Raton, Florida.

## Two Worlds

World 1: “Euclidean vector space”,

$$\mathfrak{R}^n = \left\{ \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix} : y_1, \dots, y_n \in \mathfrak{R} \right\}$$

World 2: “(Hilbert) Function Space”,

$$L^2 = \left\{ f(x) : \int_0^1 f(x)^2 dx < \infty \right\}$$

**Connection:** via “digitization”

For equally spaced  $0 \leq x_1 < \dots < x_n \leq 1$ ,

Relate  $f(x)$  to  $\begin{pmatrix} f(x_1) \\ \vdots \\ f(x_n) \end{pmatrix}$

## Inner Product Structure

World 1:

$$\langle \underline{y}, \underline{z} \rangle = \left\langle \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix}, \begin{pmatrix} z_1 \\ \vdots \\ z_n \end{pmatrix} \right\rangle = \sum_{i=1}^n y_i z_i$$

World 2:

$$\langle f, g \rangle = \int_0^1 f(x)g(x)dx$$

Consequences:

1. “distance” =  $\sqrt{\langle a - b, a - b \rangle}$
2. “angle”:  $a \perp b \iff \langle a, b \rangle = 0$

**Connection:** Riemann Summation

## Linear Bases

$\{\mathbf{y}_1, \mathbf{y}_2, \dots\}$  is a “basis” means every member  $f$  has a **linear representation**:

$$f = \sum_i q_i \mathbf{y}_i$$

A basis is “orthonormal” when:

$$\langle \mathbf{y}_i, \mathbf{y}_j \rangle = \begin{cases} 0 & i \neq j \\ 1 & i = j \end{cases}$$

(all orthogonal to each other, with length 1)

# Orthonormal Bases

Consequences:

- Compute  $\mathbf{q}_i = \langle f, \mathbf{y}_i \rangle$
- in  $\mathfrak{R}^n$ ,  $\mathbf{q} = \begin{pmatrix} \mathbf{q}_1 \\ \vdots \\ \mathbf{q}_n \end{pmatrix}$  is the “transform”
- transform is a “rotation” operation  
(lengths and angles preserved)

## Example 1: Unit vector basis

$$\underline{u}_i = \begin{pmatrix} 0 \\ \vdots \\ 0 \\ 1_i \\ 0 \\ \vdots \\ 0 \end{pmatrix} \in \mathfrak{R}^n, \quad i = 1, \dots, n$$

Notes:

- orthonormal

- for  $\underline{y} = \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix}$ , transform has  $\mathbf{q}_i = y_i$

- “identity rotation”

## Example 2: Fourier Basis

Show FourierBasis.ps, with sin's and cos's.

World 1: Discrete Fourier Basis

World 2: Continuous Fourier Basis

Exactly orthonormal in **both** (takes trigonometry)

Fourier Transform: Rotation that  
“decomposes into periodicities”

## Example 3: Haar Wavelet Basis

Show HaarFullBasis.ps

“Up and Down” step functions,  $\mathbf{y}_{j,k}$

“doubly indexed” by:

- “scale”  $j$
- “location”  $k$

“dilation form”:  $\mathbf{y}_{j,k}(x) = 2^{-j/2} \mathbf{y}(2^{-j}x - k)$

Exactly orthonormal in **both** worlds

Dyadic structure, very similar to cascades

Histogram View: successive differences

Show HaarHisto.ps



## Example 4: Smoother Wavelet Bases

Daubechies 4: Continuous but “rough”

Show Daub4Basis.ps

Symmlet 8: much smoother, still “local”

Show Symm8Basis.ps

## Application 1: Signal Compression

Idea: represent  $\underline{y}$  by transform  $\underline{q}$ , and hope that “many  $q_i \approx 0$ ”

- “lossless compression”, want  $q_i = 0$
- “approximate compression”, replace  $q$  by 0 when “close”

Main Concept:

“Good Compression”  $\Leftrightarrow$  more  $q_i \approx 0$

## Quality of approximation:

Measure by “Energy” in signal:

$$E_{\underline{y}} = \sum_{i=1}^n y_i^2 \quad \text{or} \quad E_f = \int_0^1 f(x)^2 dx$$

- lossless compression:  $E_{\underline{y}} = E_{\underline{q}}$   
(Parseval Identity)
- Good approximation:  $E_{\underline{y}} \approx E_{\underline{q}}$
- Bad approximation:  $E_{\underline{y}} \gg E_{\underline{q}}$

## Approximation Folklore:

Unit vectors: terrible for interesting signals

Fourier basis: good for smooth and periodic

Wavelet bases: allow some jumps

$\exists$  many variations, and ways of “cooking up good bases”

Show ExactRiskEGs.ps and CompressionEG.ps

## Application 2: Denoising

Goal: from “data”  $\underline{y} = \underline{s} + \underline{n}$

try to recover “signal”  $\underline{s}$

from “noise”  $\underline{n}$ , (e.g. i.i.d. mean 0)

Transform approach:

- find “rotation” with “good compression of signal”
- zero out small  $\mathbf{q}_i$
- invert transform

# Denoising Examples

Show WaveDNFourier.eps, StepDNFourier.eps and WaveStepDNHaar.eps

## Wave Target:

- Fourier basis: Excellent
- Haar basis: Poor

## Step Target:

- Fourier basis: Terrible
- Haar basis: Excellent

Note: driven by signal compression

# Fast Computation

of transform:  $\mathbf{q}_i = \langle \mathbf{y}_i, \mathbf{y}_i \rangle$ ,  $i = 1, \dots, n$

1. Naïve implementation:  $O(n^2)$  matrix multiplication
2. Fast Fourier Transform:  $O(n \log n)$  using trigonometric properties
3. Fast wavelet Transform:  $O(n)$  using simple “pyramid algorithm”

# Haar Pyramid Algorithm, I

Notation:  $\underline{1}(n) = \begin{pmatrix} 1 \\ \vdots \\ 1 \end{pmatrix}, \quad \underline{0}(n) = \begin{pmatrix} 0 \\ \vdots \\ 0 \end{pmatrix}$

“mothers”:  $\underline{y}_{j,k} = 2^{\frac{-j}{2}} \begin{pmatrix} \underline{0} \left( \frac{kn}{2^j} \right) \\ -\underline{1} \left( \frac{n}{2^{j+1}} \right) \\ \underline{1} \left( \frac{n}{2^{j+1}} \right) \\ \underline{0} \left( n - \frac{(k+1)n}{2^j} \right) \end{pmatrix}$

Show HaarFullBasis.ps again



## Haar Pyramid Algorithm, II

“fathers”:

$$\underline{\mathbf{j}}_{j,k} = 2^{\frac{-j}{2}} \begin{pmatrix} \underline{0} \left( \frac{kn}{2^j} \right) \\ \underline{1} \left( \frac{n}{2^j} \right) \\ \underline{0} \left( n - \frac{(k+1)n}{2^j} \right) \end{pmatrix}$$

Show HaarFathers.ps

Note: father vectors are also a basis (but not orthonormal)

Can mix and match mothers and fathers

Show HaarPartBasis.ps

# Haar Pyramid Algorithm, III

Relations across scales:

1. Magnification (dilation):

$\mathbf{j}_{j+1}$  is “half width” of  $\mathbf{j}_j$

$\mathbf{y}_{j+1}$  is “halfwidth” of  $\mathbf{y}_j$

2. Father  $\rightarrow$  Mother, Father

$$\underline{\mathbf{y}}_{j,k} = \frac{1}{\sqrt{2}} \left( \underline{\mathbf{j}}_{j+!,2k+1} - \underline{\mathbf{j}}_{j+!,2k} \right)$$

$$\underline{\mathbf{j}}_{j,k} = \frac{1}{\sqrt{2}} \left( \underline{\mathbf{j}}_{j+!,2k+1} + \underline{\mathbf{j}}_{j+!,2k} \right)$$

## Haar Pyramid Algorithm, IV

Apply inner product to get:

$$\mathbf{q}_{j,k} = \frac{1}{\sqrt{2}} (f_{j+1,2k+1} - f_{j+1,2k})$$

$$f_{j,k} = \frac{1}{\sqrt{2}} (f_{j+1,2k+1} + f_{j+1,2k})$$

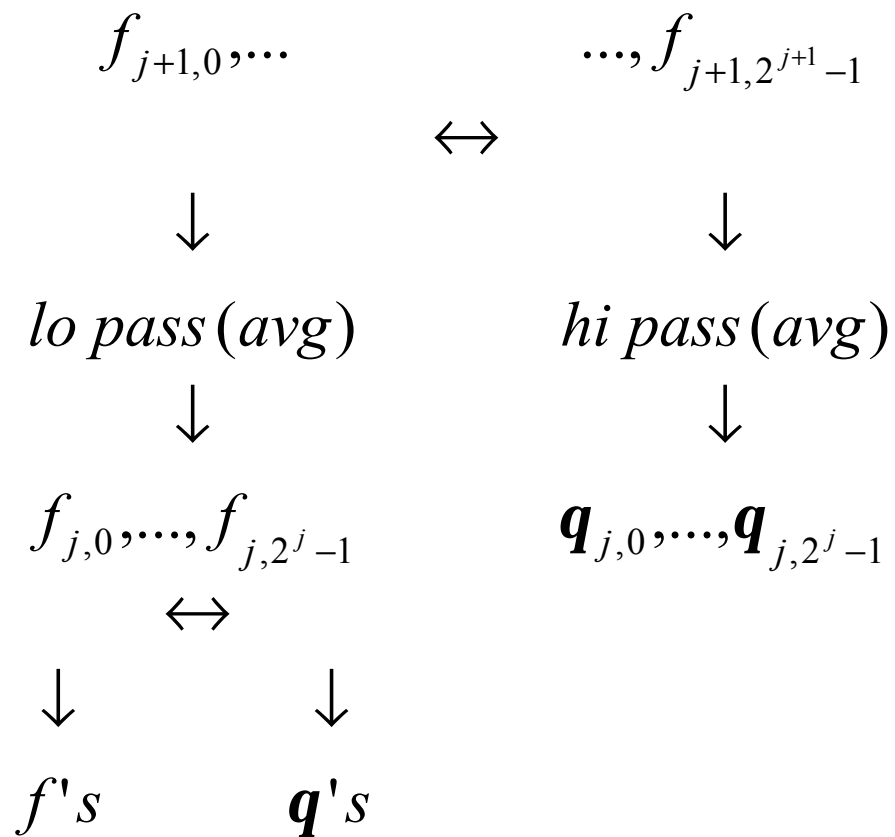
where

$$f_{j,k} = \langle \underline{\mathbf{j}}_{j,k}, \underline{\mathbf{y}} \rangle$$

Start with  $f_{\log_2(n),k} = y_k$ , and iterate up through scales, to get  $O(n)$  algorithm

# Haar Pyramid Algorithm, V

Overall Structure:



# Haar Pyramid Algorithm, VI

Notes:

1. each level is “energy preserving”:

$$\sum_{k=0}^{2^{j+1}-1} f_{j+1,k}^2 = \sum_{k=0}^{2^j-1} f_{j,k}^2 + \sum_{k=0}^{2^j-1} \mathbf{q}_{j,k}^2$$

2. “Energy of constants” passed to  $f$ ’s
3. “Anti-constant energy” passed to  $\mathbf{q}$ ’s

Again visit ExactRiskEGs.ps and CompressionEG.ps

4. “Energy issues” are ANOVA style decomposition of sums of squares